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Rajaram D. Patil 2 1, 2 M.E. Electronics, Electronics Department, P.V.P.I.T Budhgaon, Maharashtra, India Jinay7@rediffmail.com , Prajaram2@gmail.com Abstract The Authors Are Designing The Quad-copter (UAVs) For Border Security With GUI System. Now-a- Jun 3th, 2024Autonomous Quadcopter Docking SystemIn This Project A System Was Designed To Autonomous Land A Quadcopter Using Software And Materials Easily Accessible Feb 4th, 2024QUADCOPTER FLIGHT MECHANICS MODEL AND CONTROL ...Abstract: In This Thesis I Am Working On Designing The Controller For The Non-linear Quadcopter Model. The Controller Is Finely Tune Apr 4th, 2024.
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