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TD=0. Similarly, PID Controller Can Be Used As PI And PD Controller, By Removing D-action ($T_d = 0$) And I-action ($T_I = \text{Maximum}$) Respectively. Fig 3. Step Response Of The System This Graph Is Recorded In Process History View In DeltaV Of Real Time Experimentation In Open Loop. To Find The Transfer Function Of Open Loop System Above Graph Is Used.
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