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Basics Control Wrapup Kinematic Modelling Goal:

Determine The Robot Speed  $\xi^{\cdot} = X^{\cdot} Y^{\cdot} \theta^{\cdot} T$  As A Function Of Wheel Speed  $\phi$ , Steering Angle  $\beta$ , Steering Speed  $\beta^{\cdot}$  And The Geometric Parameters Of The Robot. Forwar Mar 3th, 2024.

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