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Open Box With Square Base: Figure 3.53 S X2 4xh 108 You Can Verify Your Answer In Example 1 By Using A Graphing Utility To Graph The Volume Function Use A Viewing Window In Which And And Use The Maximum Or Trace Feature To Determine 3th, 2024

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In Contrast To This, In Continuous Optimization We Will Focus On,  $X$  Is A "continuum" Set Like The Entire  $\mathbb{R}^n$ , A Box  $F_x : A \leq X \leq B$ , Or Simplex  $F_x : \sum_{j=1}^n x_j = 1, x_j \geq 0$ , Etc., And The Objective And The Constraints Are (at Least) Continuous On  $X$ . |In L 1th, 2024

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This Solution Space Contains (and Can Be Equal To) The Global Optimal Set  $X^*$ . There May Exist Valid Solutions  $X \in S$  Which Are Not Elements Of The  $X^*$ , Especially In The Context Of Constraint Optimization (see Section 1.2.3). The Search Space Definition 1.21 (Search Space). The Search Space  $G$  Of An Optimization Problem Is The 2th, 2024

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