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Topic #14 16.31 Feedback Control Full-state Feedback ...X State Step Response X 1
X 2 0 0.5 1 1.5 2 2.5 3 3.5 4 -15 -10 -5 0 5 Time (sec) U Control Step Response:
 $U = Nbar R - Kx$ $U = Nbar R - Kx$ Figure 3: Response To Step Input With The N^-
Correction. Gives The Desired Steady- Apr 16th, 2024 Dynamic Programming
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