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Feedback ...X State Step Response X 1 X 2 0 0.5 1 1.5
2 2.5 3 3.5 4 -15 -10 -5 0 5 Time (sec) U Control

Step Response: $U = Nbar R - Kx$ $U = Nbar R - Kx$ Figure 3:
Response To Step Input With The N^- Correction. Gives
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