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Dependent On The Wheel Inertia. So It Is Crucial That The Inertia Of The Tire-wheel Combination Is Simulated. The Typical Problem Is That The Dynamometer Inertia Is Greater Than The Tire-wheel Inertia. So The Simulation Must Apply A Force To The Dyno Inertia To Compensate For The Inertia Difference Feb 1th, 2024

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4 Fault Simulation Scenario Circuit Model: Mixed-level Mostly Logic With Some Switch-level For High- Impedance (Z) And Bidirectional Signals High-level Models (memory, Etc.) With Pin Faults Signal States: Logic Two (0, 1) Or Three (0, 1, X) States For Purely Boolean Logic Circuits Four States (0, 1, X Feb 1th, 2024

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