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Accumulates Experience, It Clusters Episodes Of Object Interaction To Learn The Appearance And Properties Of Novel, Unfamiliar Objects. This Process Is Called Open Object Recognition [3]. An Operator Can Then Introduce Names For Objects To Facilitate Further Task-related Communication. I. ACTIVE SEGMENTATION Mar 1th, 2024

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Momentum-based Control Strategy In Case Of Balancing In A Dynamic Environment. The Remaining Of The Paper Is Organized As Follows. SectionIIrecalls Notation, Robot Modeling And A Momentum-based Control Strategy For Balancing With Rigid, Static Con-tacts. SectionsIII-IVdetail The Modeling And Control Frame-Author: Gabriele Nava, Daniele Pucci, Nuno Guedelha, Silvio Traversaro, Francesco Romano,

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Keywords-Swarm Robotics, Bio-inspired Robotics, Collective Decision Making. I.
INTRODUCTION In The Last Decade, Swarm Robotics Is Getting Momentum, Both On
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