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3.14 Radar, Contact Level Sensors Guided Wave Radar (TDR ...

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And Assume The Vector Representative Of The Motion Of Scatterers V = (u,v,w) Varies Linearly Around Its Value (u0,V0,w0) At A Point (x0,y0,Z0), I.e., ... Especially In View Of Computing The Hori Zontal Divergence. For This Reason, Use Of The VAD ... Partly Contaminates Vt And F5 (divergence Com Ponents) And Partly Vz (vertical Velocity). Apr 2th, 2024

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