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Instructor: Dr. Y. Zeng, UH 4012 Time & Location: TR,

2PM { 3:15PM, UH 4002 ffi Hours: Tuesdays

3:30PM{4:30PM (or By Appointment) Text: A Set Of

Class Notes (evolved From Courses Taught By Several Faculty Members In The Department) Will Be Provided.

These Notes Contain All De Nititions, Theorems, And

Examples, Jan 3th, 202425. Ordinary Differential

Equations: Systems Of EquationsORDINARY

DIFFERENTIAL EQUATIONS: SYSTEMS OF EQUATIONS 5

25.4 Vector Fields A Vector field On R^m Is A Mapping $F:$

$R^m \rightarrow R^m$ That Assigns A Vector In R^m To Any Point In

R^m . If A Is An $M \times M$ matrix, We Can Define A Vector

field On R^m By $F(x) = Ax$. Many Other Vector fields Are

Possible, Such As $F(x) = x^2$ Jan 1th, 2024.

LINEAR FIRST ORDER Ordinary Differential

EquationsDifferential Equations Which Is Covered In

The Next Few Slides. For A Review Of The Direct

Method To Solve Linear First-order Differential

Equations, Jump Ahead To The Direct Method On Slide

14. The Property •Solving Differential Equations Is

Based On The Property That Mar 2th, 20242 Order

Linear Ordinary Differential Equations4 Constant

Coefficient Ordinary Differential Equations $A \frac{dy}{dx} + B$

$\frac{dy}{dx} + Cy = 2$ Where A, B And C Are Constants

The Form Of The Differential Equation Suggests

Solutions Of $Y = e^{-Cx} R(x)$. (At This Point This Form Is

Deduced By Understanding The Properties Of

Differentiating e^{Cx} . Later, Jun 1th, 2024Nd Order Linear

Ordinary Differential Equations Variation Of Parameters
 This Method Can Be Used Anytime You Already Know
 One Solution, $y_1(x)$, To The Homogeneous Form Of The
 General Differential Equation Given Below. $y'' + p(x)y' + q(x)y = r(x)$
 The Complete Solution
 Is Found By Substituting $y = y_1(x)u(x)$ Into The Above
 Differential Mar 1th, 2024.

Linear Algebra And Differential Equations Alexander
 Givental "Equations" Taught To Sophomore Students At
 UC Berkeley. We Accept The Currently Acting Syllabus
 As An Outer Constraint And Borrow From The Official
 Textbooks Two Examples, 1 But Otherwise We Stay
 Rather Far From Conventional Routes. In Particular, At
 Least Half Of The Time (Chapters 1 And 2) Is Spent To
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 Contain The Usual Topics That Jan 3th, 2024 Differential
 Equations And Linear Algebra Notes Linear Or
 Nonlinear. A Second Order ODE Is Said To Be Linear If
 It Can Be Written In The Form $A(t)y'' + B(t)y' + C(t)y = F(t)$, (1.8) Where The Coefficients $A(t)$, $B(t)$ &
 $C(t)$ Can, In General, Be Functions Of t . An Equation
 That Is Not Linear Is Said To Be Nonlinear. Note That

Linear ODEs Are Characterised By Two Properties: Jan 3th, 2024.

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